Temporal coherence

Michael Goldstein Dept. of Mathematical Sciences Durham University

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When data arrives, Bayes theorem tells you how to move from your prior probabilities to new conditional probabilities for the quantities of interest.

If you need to make decisions, then you may also specify a utility function, given which your preferred decision is that which maximises expected utility with respect to your conditional probability distribution.

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This distinction is of particular relevance in complex problems with too many sources of information for us to be comfortable in making a meaningful full joint prior probability specification of the type required for a BAYESIAN ANALYSIS. Therefore, we seek methods of prior specification and analysis which do not require this extreme level of detail.

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Thus, the Bayes linear approach is similar in spirit to a full Bayes analysis, but is based on a simpler approach to prior specification and analysis, and so offers a practical methodology for analysing partially specified beliefs for large problems.

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[2] Adjusted expectation is numerically equivalent to conditional expectation in the particular case where D comprises the indicator functions for the elements of a partition, i.e. where each D_i takes value one or zero and precisely one element D_i will equal one, eg, if B is the indicator for an event, then

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Within the Bayes linear view, Bayes analysis is a special case of no greater or lesser interest than any other special case.

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What is the relationship between our current beliefs and our future beliefs?

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[With payoffs in probability currency, expectation for the penalty equals the probability of the reward. Therefore, changes in preferences between penalties A and B over time correspond to changes in probability, rather than utility.]

Constraints on temporal preference

Current preference for random penalty A over penalty B, even when constrained by conditional statements about preferences given possible future evidential outcomes, cannot require you to hold certain future preferences; for example, you may obtain further, hitherto unsuspected, information or insights into the problem before you come to make your future judgments.

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[This is not a rationality requirement. It is a (weak) operationally testable principle which will often appear reasonable and which has important consequences for statistical reasoning.]

We treat expectation as the primitive quantification for our approach. We follow the development of de Finetti, and define the expectation of a random quantity, Z as the value \bar{z} that you would choose for z, if faced with the penalty $L = k(Z - z)^2$, where k is a constant defining the units of loss, and the penalty is paid in probability currency.

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Therefore, adjusted expectation is a prior inference for your actual posterior judgments, which resolves a portion of your current variance for \boldsymbol{B} . If \boldsymbol{D} represents a partition, $E_T(\boldsymbol{B}) = E_{\boldsymbol{D}}(\boldsymbol{B}) + \boldsymbol{R} = E(\boldsymbol{B}|\boldsymbol{D}) + \boldsymbol{R}$ where $E(\boldsymbol{R}|\boldsymbol{D}_i) = 0, \forall i$.

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De Finetti's representation theorem shows that if coin tosses are exchangeable, then all of our beliefs about coin tosses are exactly the same as if we believed that our observations were a random series of tosses of a coin with a "'true but unknown" value for the probability of heads.

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The representation theorem allows us to express beliefs about unobservable quantities purely in terms of our beliefs about observable quantities.

The only (but major) problem with this representation is that, to use the representation theorem, we must specify all of our beliefs over all the outcomes of possible collections of coin tosses of all sample sizes.

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the mean, variance and covariance structure is invariant under permutation, namely

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We may represent each X_i as the sum of an underlying 'population mean' M, and individual variation R_i , i.e.

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the mean, variance and covariance structure is invariant under permutation, namely

$$E(\boldsymbol{X}_i) = \mu, Var(\boldsymbol{X}_i) = \Sigma, Cov(\boldsymbol{X}_i, \boldsymbol{X}_j) = \Gamma, \forall i \neq j$$

We may represent each X_i as the sum of an underlying 'population mean' M, and individual variation R_i , i.e.

$$X_i = M \oplus R_i$$

where the vectors $M, R_1, R_2, ...$ are mutually uncorrelated, and

 $E(\mathbf{M}) = \mu, Var(\mathbf{M}) = \Gamma, E(\mathbf{R}_i) = 0, Var(\mathbf{R}_i) = \Sigma - \Gamma, \forall i$

Suppose that X_i is SOE (to you, now) so $X_i = M \oplus R_i$. Suppose that you will observe, at time T, a sample $(X_{[n]} = X_1, ..., X_n)$ and revise all your judgements about all remaining X_j

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$$\begin{aligned} \mathbf{X}_{j} - \mathrm{E}(\mathbf{X}) &= \mathbf{M} - \mathrm{E}(\mathbf{M}) + \mathbf{R}_{j} \\ &= [\mathbf{M} - \mathrm{E}_{T}(\mathbf{M})] \\ &\oplus [\mathrm{E}_{T}(\mathbf{M}) - \mathrm{E}_{n}(\mathbf{M})] \\ &\oplus [\mathrm{E}_{n}(\mathbf{M}) - \mathrm{E}(\mathbf{M})] \\ &\oplus [\mathrm{E}_{n}(\mathbf{M}) - \mathrm{E}(\mathbf{M})] \\ &\oplus [\mathbf{R}_{j} - \mathrm{E}_{T}(\mathbf{R}_{j})] \\ &\oplus [\mathrm{E}_{T}(\mathbf{R}_{j})] \end{aligned}$$

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The subjectivist approach offers a coherent language and tool set for analysing all of the uncertainties in complicated problems, and therefore provides the best method that I know for analysing uncertainty in complex real world problems.
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