

# Imprecise Two-Stage Maximum Likelihood Estimation

Lev Utkin

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## Initial statistical data

- 1 We have a set of observations  $\mathbf{X} = (x_1, \dots, x_n)$ , for instance, the successive intervals between failures.
- 2  $x_1, \dots, x_n$  are a realization of random variables  $X_1, \dots, X_n$ . The r.v.  $X_i$  is governed by a pdf  $p_i(x | \mathbf{b}_i, \mathbf{d})$  with vectors of parameters  $\mathbf{b}_i, \mathbf{d}$ .
- 3 It is assumed that there exists a function  $f(i, \mathbf{b}, \mathbf{d})$  such that the vector  $\mathbf{b}_i$  completely depends on the number  $i$  and the vectors of parameters  $\mathbf{b}, \mathbf{d}$  through the function  $f$ , i.e.,  $\mathbf{b}_i = f(i, \mathbf{b}, \mathbf{d})$ .

## A standard way for computing the parameters

The likelihood function is

$$\begin{aligned} L(\mathbf{X} \mid \mathbf{b}, \mathbf{d}) &= \Pr\{X_1 = x_1, \dots, X_n = x_n\} \\ &= \prod_{i=1}^n p_i(x_i \mid \mathbf{b}_i, \mathbf{d}). \end{aligned}$$

Values of the parameters  $\mathbf{b}$ ,  $\mathbf{d}$  should be chosen in such a way that makes  $L(\mathbf{K} \mid \mathbf{b}, \mathbf{d})$  achieve its maximum.

## Problems we could meet

- 1 A large number of parameters and the small amount of statistical data:
  - it is difficult to estimate the actual impact of every parameter;
  - it is difficult to compute the optimal values of parameters.
- 2 The precise distribution or pdf  $p_i$  might be unknown. We can say only about some set of distributions  $\mathcal{M}_i$  due to:
  - the limited amount of statistical data.

## The first obvious idea (1)

**The first obvious idea following from the second problem:**

Every  $X_i$  is governed by an unknown CDF belonging to a set  $\mathcal{M}_i(\mathbf{d})$  depending on a vector of parameters  $\mathbf{d}$  and defined by **lower and upper CDFs**:

$$\underline{F}_i(x | \mathbf{d}) = \inf_{F(x) \in \mathcal{M}_i(\mathbf{d})} F(x), \quad \overline{F}_i(x | \mathbf{d}) = \sup_{F(x) \in \mathcal{M}_i(\mathbf{d})} F(x).$$

## The first obvious idea (2)

### IMPORTANT:

- 1  $\mathcal{M}_i(\mathbf{d})$  is the set of *all* CDFs bounded by  $\underline{F}_i(k | \mathbf{d})$  and  $\overline{F}_i(k | \mathbf{d})$ , so it is *not* the set of parametric distributions having the same parametric form as the bounding distributions.
- 2  $\mathcal{M}_i(\mathbf{d})$  depends on  $\mathbf{d}$ .
- 3 We can not now maximize of the standard likelihood function over parameters. What can we do?

## The second idea: maximum of the likelihood function over the set of CDFs

- 1 The standard likelihood function is the joint probability which has to be maximized over sets of parameters. But we have a set of probabilities. Therefore, we choose the largest probability in the set, i.e., we maximize the likelihood function over the set of probabilities depending on  $\mathbf{d}$ .
- 2 **Let us fix the parameters  $\mathbf{d}$ .**
- 3 The likelihood function  $L(\mathbf{X} \mid \mathbf{d}, F)$  is maximized over all distributions  $F$  from  $\mathcal{M}_i(\mathbf{d})$  and the resulting “modified” likelihood function depends on  $\mathbf{d}$ :

$$L^*(\mathbf{X} \mid \mathbf{d}) = \max_{F \in \mathcal{M}_1(\mathbf{d}), \dots, F \in \mathcal{M}_n(\mathbf{d})} L(\mathbf{X} \mid \mathbf{d}, F).$$

## The third idea: maximum of the “modified” likelihood function over the set of parameters $\mathbf{d}$

By assuming that the “modified” likelihood function  $L^*(\mathbf{X} \mid \mathbf{d})$  depends on  $\mathbf{d}$ , we maximize it over the set of  $\mathbf{d}$  in order to find  $\mathbf{d}$ , i.e.,

$$L^*(\mathbf{X} \mid \mathbf{d}) \rightarrow \max_{\mathbf{d}}.$$



## Returning to the second idea: maximum of the likelihood function over the set of CDFs

- In other words, we have to find optimal distribution functions in every  $\mathcal{M}_i(\mathbf{d})$  which *can* depend on  $\mathbf{d}$ .
- How to find them?

## The maximized likelihood function (discrete case)

### Proposition

*If random variables  $X_1, \dots, X_n$  are independent and discrete, then there holds*

$$\max_{\mathcal{M}} \Pr \{X_1 = x_1, \dots, X_n = x_n\} = \prod_{i=1}^n \{\bar{F}_i(x_i) - \underline{F}_i(x_i - 1)\}.$$

## “Precise” case

### Corollary

If  $\bar{F}_i(x) = \underline{F}_i(x) = F_i(x)$ , then

$$\max_{\mathcal{M}} \Pr \{X_1 = x_1, \dots, X_n = x_n\} = \prod_{i=1}^n p_i(x_i) = L(\mathbf{X} \mid \mathbf{d}).$$

Here  $p_i(k)$  is the probability mass function corresponding to the distribution function  $F_i(k)$ .

We have the standard likelihood function.

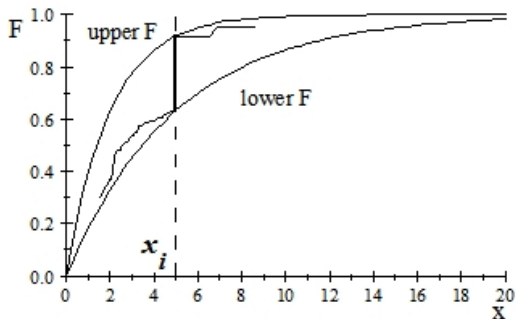
# The maximized likelihood function (continuous case)

## Proposition

*If random variables  $X_1, \dots, X_n$  are independent and continuous, then there holds*

$$\max_{\mathcal{M}} \Pr \{X_1 = x_1, \dots, X_n = x_n\} = \prod_{i=1}^n \{\bar{F}_i(x_i) - \underline{F}_i(x_i)\} \delta(x_i).$$

## Optimal distribution function (continuous case)



# The maximized likelihood function (the lack of independence)

## Proposition

*If there is no information about independence of random variables  $X_1, \dots, X_n$ , then there holds*

$$\max_{\mathcal{M}} \Pr \{X_1 = x_1, \dots, X_n = x_n\} = \min_{i=1, \dots, n} \{ \bar{F}_i(x_i) - \underline{F}_i(x_i - 1) \}.$$

## “Precise” case

### Corollary

If  $\bar{F}_i(x) = \underline{F}_i(x)$ , then

$$\max_{\mathcal{M}} \Pr \{X_1 = x_1, \dots, X_n = x_n\} = \min_{i=1, \dots, n} p_i(x_i).$$

We have the possibilistic likelihood function.

Returning to the third idea: maximum of the “modified” likelihood function over the set of parameters  $\mathbf{d}$

$$L^*(\mathbf{X} \mid \mathbf{d}) = \bigotimes_{i=1}^n \{ \bar{F}_i(x_i \mid \mathbf{d}) - \underline{F}_i(x_i - 1 \mid \mathbf{d}) \} \rightarrow \max_{\mathbf{d}}.$$

Here the operator  $\bigotimes$  can be  $\prod$  (independence) or  $\min$  (unknown interaction).



# The next problem is how to construct the lower and upper CDFs

Three obvious methods can be proposed:

- 1 Using the imprecise Bayesian models.
- 2 Using the method of moments.
- 3 Using the confidence intervals on the mean and variance.

# The imprecise Bayesian inference models

- 1 Imprecise Dirichlet model (Walley 1996);
- 2 Imprecise models for inference in exponential families (Quaeghebeur and de Cooman 2005).

The lower and upper CDFs for  $\mathcal{M}_i(\mathbf{d})$  are constructed by means of **an imprecise Bayesian model** conditioned on the parameters  $\mathbf{d}$  and the function  $f(i, \mathbf{b}, \mathbf{d})$ . The parameters  $\mathbf{b}$  are replaced by **caution parameter**  $s$  or parameters  $s_1, s_2$ . The **imprecision** of the model is defined by the caution parameter  $s$ .

## The imprecise method of moments (1)

By having  $k$  moments, we can restrict a set of probability distributions (or pdfs) by the constraints:

$$\mathbb{E}(x^i) = m_i(\mathbf{d}), \quad i = 1, \dots, k,$$

or

$$\sum_{j=1}^N p(v_j) v_j^i = \frac{1}{n} \sum_{j=1}^n x_j^i, \quad i = 1, \dots, k,$$

or

$$\int_{-\infty}^{\infty} v^i p(v) dv = \frac{1}{n} \sum_{j=1}^n x_j^i, \quad i = 1, \dots, k.$$

Here  $p \in \mathcal{M}$ . In other words, the set of sample moments produces the set  $\mathcal{M}$ .

The imprecision is defined by a number of moments.

## The imprecise method of moments (2)

The parametric (with parameters  $\mathbf{d}$ ) linear programming:

$$\underline{F}(x \mid \mathbf{d}) = \min_p \sum_{j=1}^N p(v_j) I_{(-\infty, x]}(v_j),$$

$$\overline{F}(x \mid \mathbf{d}) = \max_p \sum_{j=1}^N p(v_j) I_{(-\infty, x]}(v_j),$$

subject to

$$\sum_{j=1}^N p(v_j) v_j^i = m_i(\mathbf{d}), \quad i = 1, \dots, k.$$

In regression models:  $x_j = y_j - f(\mathbf{x}_j, \mathbf{d})$  and:

$$m_i(\mathbf{d}) = \frac{1}{n} \sum_{j=1}^n (y_j - f(\mathbf{x}_j, \mathbf{d}))^i.$$

## The imprecise method of moments (3)

The parametric (with parameters  $\mathbf{d}$ ) linear programming:

$$\underline{F}(x \mid \mathbf{d}) = \min_p \int_{-\infty}^{\infty} I_{(-\infty, x]}(v) p(v) dv,$$
$$\overline{F}(x \mid \mathbf{d}) = \max_p \int_{-\infty}^{\infty} I_{(-\infty, x]}(v) p(v) dv,$$

subject to

$$\int_{-\infty}^{\infty} v^i p(v) dv = m_i(\mathbf{d}), \quad i = 1, \dots, k.$$

In regression models:  $x_j = y_j - f(\mathbf{x}_j, \mathbf{d})$  and:

$$m_i(\mathbf{d}) = \frac{1}{n} \sum_{j=1}^n (y_j - f(\mathbf{x}_j, \mathbf{d}))^i.$$

## The imprecise method of moments (4): example - Chebyshev's inequality

We take only two moments and obtain Chebyshev's inequality.  
Bounds for the CDF are

$$\underline{F}(t | \mathbf{d}) = \begin{cases} 1 - \frac{m_2(\mathbf{d}) - m_1^2(\mathbf{d})}{(m_1(\mathbf{d}) - t)^2 + m_2(\mathbf{d}) - m_1^2(\mathbf{d})}, & t \geq m_1(\mathbf{d}) \\ 0, & t < m_1(\mathbf{d}) \end{cases},$$

$$\bar{F}(t | \mathbf{d}) = \begin{cases} \frac{m_2(\mathbf{d}) - m_1^2(\mathbf{d})}{(m_1(\mathbf{d}) - t)^2 + m_2(\mathbf{d}) - m_1^2(\mathbf{d})}, & t \leq m_1(\mathbf{d}) \\ 1, & t > m_1(\mathbf{d}) \end{cases}.$$

## Confidence intervals on the mean and variance

95% confidence intervals on the mean and variance ( $\alpha = 0.05$ ):

$$[\underline{m}_1(\mathbf{d}), \bar{m}_1(\mathbf{d})] = \left[ m_1(\mathbf{d}) - \frac{t_{\alpha/2, N-1} \hat{\sigma}(\mathbf{d})}{\sqrt{N}}, m_1(\mathbf{d}) + \frac{t_{\alpha/2, N-1} \hat{\sigma}(\mathbf{d})}{\sqrt{N}} \right],$$

$$[\underline{\sigma}^2(\mathbf{d}), \bar{\sigma}^2(\mathbf{d})] = \left[ \frac{(N-1)\hat{\sigma}^2(\mathbf{d})}{\chi^2_{\alpha/2, N-1}}, \frac{(N-1)\hat{\sigma}^2(\mathbf{d})}{\chi^2_{1-\alpha/2, N-1}} \right],$$

$$\underline{F}(x \mid \mathbf{d}) = \min \{ \Phi((x - \bar{m}_1(\mathbf{d})) / \bar{\sigma}(\mathbf{d})), \Phi((x - \bar{m}_1(\mathbf{d})) / \underline{\sigma}(\mathbf{d})) \},$$

$$\bar{F}(x \mid \mathbf{d}) = \max \{ \Phi((x - \underline{m}_1(\mathbf{d})) / \bar{\sigma}(\mathbf{d})), \Phi((x - \underline{m}_1(\mathbf{d})) / \underline{\sigma}(\mathbf{d})) \}.$$

The imprecision is defined by  $\alpha$ . In regression models:

$$\hat{\sigma}^2(\mathbf{d}) = \frac{1}{n} \sum_{j=1}^n (y_j - f(\mathbf{x}_j, \mathbf{d}))^2 - \left( \frac{1}{n} \sum_{j=1}^n (y_j - f(\mathbf{x}_j, \mathbf{d})) \right)^2.$$

## Returning to the third idea: maximum of the “modified” likelihood function over the set of parameters $\mathbf{d}$

Now the “modified” likelihood function has been defined

$$L^*(\mathbf{X} \mid \mathbf{d}) = \bigotimes_{i=1}^n \{ \bar{F}_i(x_i \mid \mathbf{d}) - \underline{F}_i(x_i - 1 \mid \mathbf{d}) \} \rightarrow \max_{\mathbf{d}}.$$



# Questions

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